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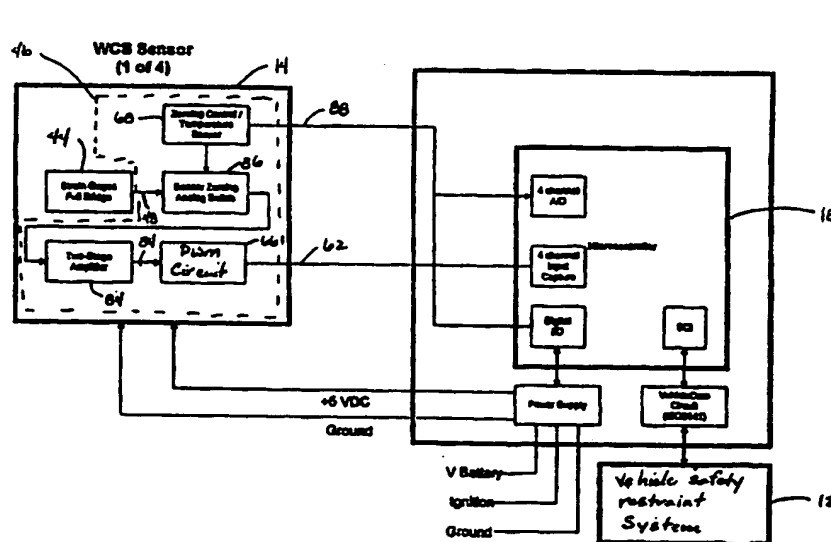
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(57) Abstract

A method and system for determining weight and/or position of a vehicle seat occupant to be used for controlling the reaction of a safety restraint system (12). A plurality of spaced weight sensors (14) are disposed between a seating surface and seat mounting surface to provide output signals indicative of an applied weight on each sensor. The sensors (14) are spaced such that the sensors measure the weight applied to a seat back and the seating surface. A controller (18) calculates the weight and/or position of the seat occupant in response to the output signals of the sensors (14). The controller (18) sends the weight and position of the seat occupant to the safety restraint system (12) to be used to tailor or suppress the reaction of the safety restraint system (12).

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A METHOD AND SYSTEM FOR DETERMINING WEIGHT AND POSITION OF A VEHICLE SEAT OCCUPANT

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Field of the Invention

This invention relates to vehicle safety restraint systems and more particularly to a method and system for controlling the reaction of safety restraint systems in response to weight and position of a vehicle occupant.

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Background of the Invention

It is known in the art relating to vehicle safety restraint systems to adjust the reaction of the restraint system to accommodate for the weight and position of the vehicle occupant. It is desirable to prevent injury and unnecessary deployment of the safety restraint system. Deployment of an air bag associated with an unoccupied seat location during a vehicle crash adds unnecessary expense to repair of the vehicle. Also, it is desirable to prevent deployment of the air bag when a small child, or an infant in a rear facing car seat, is occupying the seat.

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To prevent such unnecessary deployment of an air bag at an unoccupied seat location, sensors are provided to detect the presence of an occupant on the vehicle seat. These sensors include pressure sensing switches located in the seat cushion or infrared or ultrasonic sensors located in the vehicle dashboard or instrument panel. A problem with the infrared or ultrasonic sensors is that if the dashboard is blocked or the seat is covered, accurate detection of a seat occupant in the seat is hindered. Also, such sensors are not cost effective. Furthermore, most prior sensing systems fail to provide an accurate weight of the seat occupant which can be used to determine and adjust the reaction of safety restraint systems.

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Another device for controlling a safety restraint system is a

manual override switch that may be installed to allow a driver to disable the passenger-side air bag manually. Such devices, however, become ineffective in instances where the driver or operator simply forgets to turn the switch on or off depending upon the existence of a passenger or a child in the vehicle seat.

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Summary of the Invention

The present invention provides a method and system for determining weight and/or position of a vehicle seat occupant to control the reaction of safety restraint systems, such as air bag modules and constant force retractors.

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An object of the present invention is to provide a system that controls the reaction of the safety restraint system in response to the weight of the seat occupant and their position. For example, if the seat occupant is a child having a low weight, the air bag module will not be deployed.

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Another object of the present invention is to modify the air bag deployment if the seat occupant is improperly seated or too close to the dashboard.

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A further object of the present invention is to modify the inflation force of the air bag module in response to the weight of the seat occupant.

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Another object of the present invention is to provide the seat occupant's seating position during pre-crash braking where the occupant's position changes rapidly due to high deceleration due to braking.

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A still further object of the present invention is to provide a more accurate weight of the seat occupant.

The method of the present invention includes sampling output

signals of a plurality of spaced weight sensors disposed between a seat surface and a seat mounting surface. The output signals of the weight sensors are added together to determine the total applied weight on a vehicle seat. The center of gravity is determined from the output signals of the weight sensors.

5 An information factor is then determined. One of the information factors determined is a seating position of the occupant. The seating position of the seat occupant is determined from the center of gravity of the occupant. Another information factor determined is a correction factor. The correction factor is used to determine an actual weight of the seat occupant.

10 The correction factor is multiplied by the total applied weight to determine the actual weight of the seat occupant. From the weight and position of the seat occupant, the seat occupant is classified into weight and position classifications. The classifications are then sent to the safety restraint system to be used to control the reaction of the safety restraint system.

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The system of the present invention includes a plurality of weight sensors disposed between a seat surface and a seat mounting surface for providing output signals indicative of an applied weight on the sensors. The sensors are spaced such that the sensors measure the applied weight on the

20 seat back and the seating surface. Each of the sensors includes a seat surface engaging portion, a seat mounting engaging portion and a walled portion extending between the engaging portions. Each walled portion includes at least one strain gage mounted thereon for measuring wall deflection which is proportional to applied weight. A controller is in communication with the weight

25 sensors for calculating at least one information factor such as weight or position of the seat occupant. The weight and/or position information is sent to the safety restraint system to be used to control the reaction of the safety restraint system.

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These and other features and advantages of the invention will be more fully understood from the following detailed description of the invention taken together with the accompanying drawings.

Brief Description of the Drawings

In the drawings:

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FIG. 1 is a block diagram of a system for determining the weight and position of a vehicle seat occupant in accordance to the present invention;

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FIG. 2 is a side view of a vehicle seat having weight sensors disposed between a seating surface and seat mounting surface;

FIG. 3 is a schematic plan view of the vehicle seat having four sensors spaced according to one embodiment of the present invention;

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FIG. 4 is a perspective view of a weight sensor;

FIG. 5 is a cross-sectional view of the weight sensor taken along line 5-5 in FIG. 4;

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FIG. 6 is a block diagram of a sensor interface circuit for providing a signal indicative of the applied weight to the vehicle seat;

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FIG. 7a is a graph of a reference signal from an integrator within the sensor interface circuit and of a strain gage output signal;

FIG. 7b is a graph of a pulse width modulation signal from the sensor interface circuit indicative of the applied weight on the seat;

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FIG. 8 is a schematic view of a seat occupant seated in a normal seating position illustrating the relationship between the occupant's distance from the dashboard and the forces applied to the seat;

FIG. 9 is a schematic view of a seat occupant seated in a forward seating position illustrating the relationship between the occupant's distance from the dashboard and the forces applied to the seat;

5 FIG. 10 is a flow diagram of the operation of the system; and

FIG. 11 is a graph of vehicle acceleration vs. time illustrating the seat occupant's position displacement during pre-braking and crash.

10 **Detailed Description of the Invention**

Referring now to the drawings, numeral 10 generally indicates a system for determining the weight and/or position of a vehicle occupant to control the reaction of a vehicle safety restraint system 12. The system 10 includes weight sensors 14 located beneath a vehicle seat 16 and a controller 18 to determine the weight and position of the vehicle occupant in response to the output signals of the weight sensors. For adaptive restraint systems, the weight and position of the seat occupant is an important parameter to adjust the reaction of safety devices such as air bags and constant force retractors in a crash situation.

The weight and position of the seat occupant can be determined by measuring the force or weight applied by the occupant to a seating surface, or seat pan 20, and to a seat back 22. A plurality of weight sensors 14 located between the seat and a designated seat mounting portion, for example, underneath the seat pan 20, are used to measure the forces applied to the seat 16. In one embodiment, the sensors 14 are disposed between the seat pan 20 and a seat mounting surface, or seat tracks 24. Alternatively, the weight sensors 14 may be disposed between the seat tracks 24 and a seat frame 26. The spacing of the sensors 14 is such that all forces applied to the seat back 22 and the seat pan 20 are measured.

In a preferred embodiment, the weight sensors 14 are located at the main connecting points of the seat pan 20 and the seat back 22 to the seat tracks 24. Referring to FIGS. 2 and 3, sensors 28,30 are located at a first connection point near the front of the seat 16 where the seat pan 20 and seat tracks 24 connect. Sensors 32,34 are located at a second connection point near the rear of the seat 16 where the seat pan 20, seat back brackets 36 and seat tracks 24 connect. Essentially, a sensor 14 is located near each corner of the seat pan 20. Such a mounting arrangement of sensors 28,30,32,34 allows for all seat pan 20 and seat back 22 forces (F_n) to be transferred through the sensors to the controller 18.

Referring to FIGS. 4 and 5, each sensor 14 includes a seat surface engaging portion 38, a seat mounting surface engaging portion 40 and a walled portion 42 extending between the engaging portions 38,40. As shown in FIG. 1, each sensor 14 includes at least one strain gage 44 mounted thereon. When a force is applied to the sensor 14 the walled portion 42 deflects and the resulting wall deflection is proportional to the applied weight. Also, the walled portion 42 may include a sensor interface circuit 46 which allows the controller 18 to analyze a strain gage output signal 48 to calculate the weight and position of the seat occupant.

For a high sensitivity in the vertical axis and a low cross sensitivity against horizontal forces, four strain gages 50,52,54,56 should be applied to the walled portion 42. Strain gages 50 and 52 are located on an inner diameter of the walled portion 42. Strain gages 54, 56 are located on an outer diameter of the walled portion 42. The strain gages 50,52 are diametrically opposite from each other and strain gages 54,56 are diametrically opposite from each other. For applications where the sensitivity and accuracy of the sensor can be decreased, only one or two strain gages may be used.

Each sensor 14 may include a full bridge or wheatstone bridge arrangement of strain gages that converts strain of the walled portion 42 to

which it is attached into resistance changes. To obtain the strain gage output signal 48, a dc voltage is applied across two of the four terminals of the bridge. The difference between the output voltages at the other two terminals is the differential output voltage signal of the strain gage 44 which is proportional to the applied weight.

Referring to FIGS. 1 and 6, each sensor 14 may include the sensor interface circuit 46 which develops a pulse width modulation (PWM) signal 62 indicative of the applied weight to the sensor 14 that is applied to the controller 18. The circuit 46 includes a two-stage signal amplifier 84, pulse width modulation circuit 66, and temperature sensor/zeroing control circuit 68. Since the strain gage output signal 48 is at such a small voltage level, the two-stage signal amplifier 84 is needed to amplify the signal to a readable level. The two-stage amplifier 84 includes two operational amplifiers 70,72.

The pulse width modulation circuit 66 includes a voltage reference circuit 74, analog integrator 76 with reset circuit 78 and comparator 80. The voltage reference circuit 74 provides a constant voltage 75 to the analog integrator 76. The constant voltage 75 is generated from a supply voltage (V_{dc}). The voltage reference circuit 74 may be a voltage divider. The constant voltage 75 is applied to the integrator 76 to generate a reference signal 82 to be compared with an amplified strain gage output signal 84.

Referring to FIGS. 6 and 7a, the voltage reference circuit 74, integrator 76 and reset circuit 78 are used to produce a saw-tooth shaped signal, or the reference signal 82, at the output of the integrator 76 to be compared with the amplified strain gage output signal 84. The reset circuit 78 may include a comparator with hysteresis that controls a switch, such as a metal-oxide semiconductor field-effect transistor (MOSFET) transistor (not shown). The reset circuit 78 is connected between the output of the integrator 76 and a capacitor (not shown) within the integrator 76. When the output signal 82 of the integrator 76 reaches a predetermined voltage level, the reset circuit

78 changes state, causing the capacitor to stop charging and begin to discharge. By charging and discharging the capacitor, the output signal 82 of the integrator 76 ramps from a low to a high voltage, producing the "saw-tooth" signal, as shown in FIG. 7a.

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The reference signal 82 and the amplified strain gage output signal 84 are applied to the comparator 80 to produce the PWM signal 62 indicative of the applied weight to the sensor. Referring to FIGS. 7a and 7b, when the voltage output of the strain gage 44 is lower than the voltage output of the integrator 76, the comparator 80 generates a logic high output. Further, when the voltage output of the strain gage 44 is higher than the voltage of the output of the integrator 76, the comparator 80 generates a logic low output. The time between pulses is proportional to the weight applied to the sensor.

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To correct voltage offsets due to varying temperature in the sensor interface circuit 46, the temperature/zero control circuit 68 is included in the circuit 46. The control circuit 68 includes a temperature sensor and sensor zeroing analog switch 86. The output signal 88 of the temperature/zero control circuit 68 is applied to the controller 18 as an analog signal. Also, multiplexed on the same output signal 88 is ability of the controller to pull the temperature sensor output signal to +5V. This causes the sensor zeroing analog switch 86 to close, removing the strain gage output signal 48 from the amplifier 64 so that the PWM signal 62 can be measured when the strain gage output signal 48 of the strain gage is zero. By having the ability to measure the PWM signal 62 at zero output, the voltage offsets can be compensated in the controller 18.

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From the PWM signal 62, the controller 18 can determine the weight of the seat occupant. Alternatively, the controller 18 can determine the center of gravity of the occupant and, then, from the center of gravity, the weight of the occupant. The center of gravity is centered somewhere within the confines of the sensor grouping. The center of gravity is determined by summing the forces applied to the sensors 28,30 near the front of the seat pan

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20 and then dividing the sum by the total of all the forces applied to the sensors 28,30,32,34. In practice, it is found that the center of weight varies depending on the occupant and their seating position.

5 In FIG. 8, the seat occupant is seated in a normal seating position and in FIG. 9, the occupant is seated in a forward seating position. It is apparent by comparing FIGS. 8 and 9 that the center of gravity of the occupant seating in the forward position is much closer to the dashboard 90 than the center of gravity of occupant seating in the normal position. Furthermore, 10 FIGS. 8 and 9 show the relationship of the seat forces for normal and forward occupant seating positions.

The measured forces are directly related to the occupant's position in the seat. The occupant's force on the seat with position is indicated 15 as the force vector, F_{occupant} . The occupant's center of gravity is the position of F_{occupant} in the seat. The measured forces at the front and rear respectively are F_f and F_r . For the normal seating position, the force at the rear, F_r is higher than the front, F_f . This is due to more of the occupant's weight located in the upper body. With a high percentage of the occupant's weight in the upper body, the 20 center of gravity is a good indication of the distance of the occupant's upper body to the dashboard 90. Alternatively, a position sensor may be mounted within the seat tracks to determine the distance between the seat and the dashboard 90. By combining the seat position and the seating position of the seat occupant, a position classification can be determined indicative of the 25 occupant's position relative to the dashboard.

For the forward seating position, the occupant's upper body is leaning forward, causing the center of gravity to shift forward as indicated. Thus, the measured force at the front, F_f is now larger than at the rear, F_r . The 30 change in the position of the upper body has a significant effect on the center of gravity. This center of gravity shift forward properly indicates a forward seated occupant, close to the dashboard 90. Thus, from the center of gravity, an

accurate weight and position of the occupant can be determined.

From the center of gravity, a correction factor is calculated. The correction factor is used to determine the actual weight of the seat occupant.

5 The correction factor is a correlation between the center of gravity and the seating position of the occupant. The correction factor may be determined by, for example, but not limited to, using appropriate correction factor algorithms or look up tables. The correction factor is needed because the measured forces are proportional to the weight applied to the seat, but not directly related to the weight of the occupant.

10 In most seating positions only a variable part of the occupant's weight is applied to the seat. The percentage of weight seen on the seat is influenced by the position of the occupant. For example, in a standard seating position about 85% of the passenger's weight is seen on the seat. The rest is mainly applied to the floor of the car through the legs. A passenger leaning forward applies more weight to the floor than a passenger in a reclined position. Thus, use of the correction factor increases the accuracy of the measured weight.

20 The controller 18 calculates the weight and/or position of the occupant by sampling the response of each sensor to applied weight to the seat. FIG. 10 is a flow diagram of the operation of the weight and position system. The algorithm is initialized in step 92 and each sensor is sampled in step 94. The controller 18 samples the sensors 14 about every 30 milliseconds. Because of such a fast sample rate, the position of the seat occupant can be measured during pre-crash braking, as shown in FIG. 11. A biased average of each sensor output signal is taken over time in step 96, allowing for a better understanding of the occupant's weight. The averages are summed together to obtain a total force or weight parameter in step 98. Then, the center of gravity is calculated in step 100. The seating position of the seat occupant is determined from the center of gravity in step 102. Also, the

correction factor is determined from the center of gravity in step 104. After the correction factor is determined, an actual weight of the occupant is found by multiplying the applied weight by the correction factor in step 106. From the weight and position of the occupant, the controller determines the weight and position classifications in step 108. The controller sends the classification information to the safety restraint system to be used to control the reaction of the safety restraint system in step 110.

Alternatively, the center of gravity is not needed to determine the weight of the occupant. If the measured weight is below a predetermined value, the occupant is considered a child, then the measured weight is the real weight. However, if the measured weight is above a predetermined value, the measured weight is multiplied by a particular correction factor for a normal seating position to obtain the real weight of the occupant. Then, the weight classification is determined and the classification to the safety restraint system.

Although the invention has been described by reference to a specific embodiment, it should be understood that numerous changes may be made within the spirit and scope of the inventive concepts described. Accordingly, it is intended that the invention not be limited to the described embodiment, but that it includes all modifications encompassed within the spirit of the following claims.

Claims

What is claimed is:

5 1. A method for determining factors to be used for controlling the reaction of a safety restraint system, said method comprising the steps of:

 sampling output signals of a plurality of spaced weight sensors disposed between a seat surface and a seat mounting surface and spaced such that forces applied to a seating surface and a seat back are measured, said output signals indicative of the applied weight to each sensor;

10 determining a total applied weight to a vehicle seat from the output signals of the weight sensors; and

 calculating a center of gravity of the seat occupant for use as an information factor.

15 2. A method as in claim 1 further comprising the steps of using the center of gravity to determine a correction factor; and

 calculating an actual weight of the seat occupant by multiplying the total applied weight by the correction factor.

20 3. A method as in claim 2 further comprising the step of determining a weight classification of the seat occupant from the actual weight of the seat occupant.

25 4. A method as in claim 3 further comprising the step of sending the weight classification to the safety restraint system to be used to control the reaction of the safety restraint system.

30 5. A method as in claim 1 further comprising the step of using the center of gravity to determine the seating position of the seat occupant.

6. A method as in claim 5 further comprising the step of

determining a seating position classification of the seat occupant.

7. A method as in claim 6 further comprising the step of sending the seating position classification to the safety restraint system to be used to control the reaction of the safety restraint system.

8. A method as in claim 5 further comprising the step of sensing a position of the vehicle seat relative to a vehicle dashboard.

9. A method as in claim 8 further comprising the step of combining the seating position of the seat occupant with the position of the vehicle seat to determine a seating position classification of the seat occupant.

10. A method as in claim 9 further comprising the step of sending the seating position classification to the safety restraint system to be used to control the reaction of the safety restraint system.

11. A method as in claim 1 wherein the step of sampling the output signals of the weight sensors includes the step of taking a biasing average of the output signals from the sensor over period a time.

12. A method as in claim 1 wherein the step of sampling the output signals of the weight sensors includes the step of developing a pulse width modulation signal indicative of the applied weight to each sensor.

13. A method as in claim 1 wherein the step of sampling of the output signals of the weight sensors includes the step of compensating for varying temperature.

14. A method as in claim 1 wherein the step of determining the center of gravity includes the steps of: summing the output signals of the sensors located at the first connection point for providing a sum;

dividing the sum by a total of the output signals from the sensors.

15 15. A method as in claim 1 wherein four weight sensors are
disposed between the seat surface and seat mounting surface, two weight
sensors located at a first connection point near a front of the seat, where the
seat surface and the seat mounting surface connect, and two weight sensors
located at a second connection point, near a rear of the seat, where the seat
surface, seat mounting surface and a seat back connect.

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16. A method as in claim 1 wherein each weight sensor
includes at least one strain gage.

17. A method for determining weight of a vehicle occupant to
control the reaction of a safety restraint system, comprising the steps of:

15 sampling output signals of a plurality of spaced weight sensors
disposed between a seat surface and a seat mounting surface and spaced
such that forces applied to a seating surface and a seat back are measured,
said output signals indicative of the applied weight to each sensor;

20 determining a total applied weight to a vehicle seat using the
output signals of the weight sensors;

 determining whether the total applied weight is above a
predetermined weight to distinguish between a child and an adult seat
occupant;

25 utilizing the applied weight as an actual weight when the applied
weight is not above the predetermined weight; and

 calculating the actual weight of the seat occupant by multiplying
the total applied weight by a correction factor for a normal seating position
when the applied weight is above the predetermined weight.

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18. A method as in claim 17 further comprising the step of
determining a weight classification of the seat occupant.

19. A method as in claim 18 further comprising the step of sending the weight classification information to the safety restraint system to be used to control the reaction of the safety restraint system.

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20. A system for providing factors to be used for controlling the reaction of a vehicle safety restraint system comprising:

a plurality of spaced weight sensors disposed between a seat surface and a seat mounting surface for providing output signals indicative of an applied weight to each sensor and spaced such that forces applied to a seating surface and a seat back are measured;

each said weight sensor including a seat surface engaging portion, a seat mounting surface engaging portion and a walled portion extending between said engaging portions;

each said walled portion including at least one strain gage mounted thereon for measuring wall deflection, and providing a strain gage output signal indicative of the applied weight; and

a controller in communication with the weight sensors and the safety restraint system for calculating an information factor, in response to the output signals of the weight sensors, to be used to control the reaction of the vehicle safety restraint system.

21. A system as in claim 20 wherein the information factor is a seating position of the seat occupant.

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22. A system as in claim 20 wherein the information factor is a weight of the seat occupant.

23. A system as in claim 20 wherein each sensor includes a sensor interface circuit comprising:

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an amplifier circuit for amplifying the strain gage output signal;

and

a pulse width modulation circuit for providing a pulse width modulation signal indicative of the applied weight to the sensor to be applied to the controller.

5 24. A system as in claim 23 further comprising a temperature control circuit for compensating for varying temperatures within the sensor interface circuit.

10 25. A system as in claim 23 wherein the amplifier circuit comprises a first operational amplifier and a second operational amplifier.

 26. A system as in claim 23 wherein the pulse width modulation circuit comprises:
 a voltage reference circuit for providing a constant voltage to an
15 integrator;
 said integrator providing a reference signal to be compared with the strain gage output signal; and
 a comparator for comparing the reference signal and the strain gage output signal to generate the pulse width modulation signal indicative of
20 the applied weight to the sensor.

 27. A system as in claim 26 wherein the integrator has a reset control circuit for restarting the reference signal when said reference signal reaches a predetermined voltage level.

25 28. A system as in claim 20 wherein the sensors are located at a first connection point near a front of the seating surface where the seating surface and the seat mounting surface connect and at a second connection point near a rear of the seating surface where the seating surface, seat
30 mounting surface and a seat back connect.

 29. A system as in claim 28 wherein four sensors are disposed

between the seat and seat mounting surface, two sensors located at the first connection point and two sensors located at the second connection point.

30. A system as in claim 20 wherein each sensor includes four
5 strain gages, two strain gages mounted on an inner diameter of the walled portion and two strain gages mounted on an outer diameter of the walled portion.

31. A system as in claim 30 wherein the two strain gages on
10 the inner diameter are diametrically opposite and the two strain gages on the outer diameter are diametrically opposite.

32. A system as in claim 20 further comprising a position
15 sensor mounted within seat tracks defining said seat mounting surface to determine the position of the seat relative to a vehicle dashboard.

33. An apparatus for controlling a vehicle safety restraint system, comprising:

a plurality of weight sensors disposed between a seat surface
20 and a seat mounting surface, each said weight sensor engaging a respective seat surface and a respective seat mounting surface, each said weight sensor providing a strain gage output; and

a controller operatively connected to a safety restraint device and
25 said plurality of weight sensors, said controller determining an information factor in response to said strain gage output, and controlling the safety restraint device in response to said information factor.

34. The apparatus as in claim 33, wherein said information
30 factor comprises center of gravity and occupant weight information.

35. The apparatus as in claim 34, wherein said information
factor comprises occupant position information.

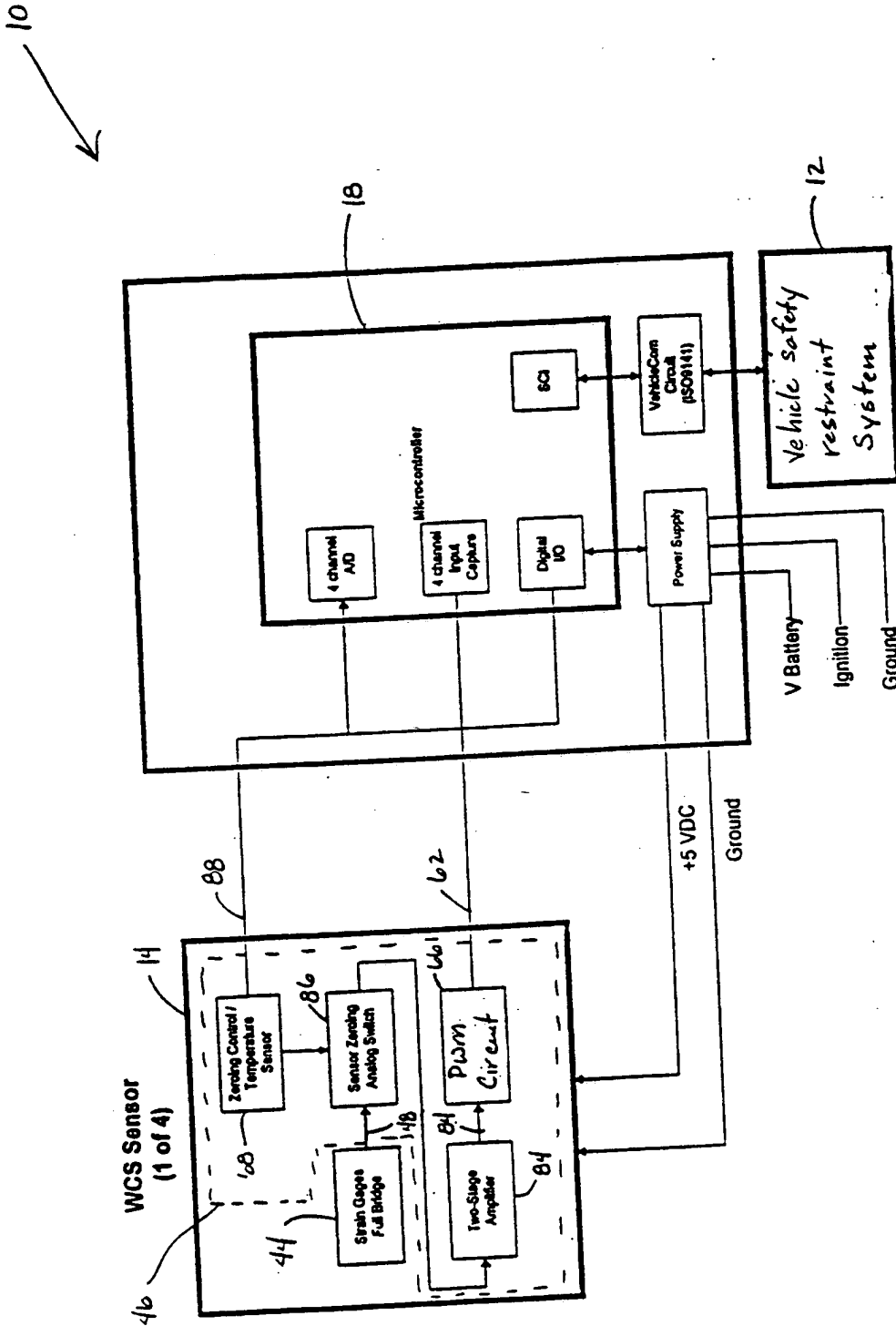


FIG. 1

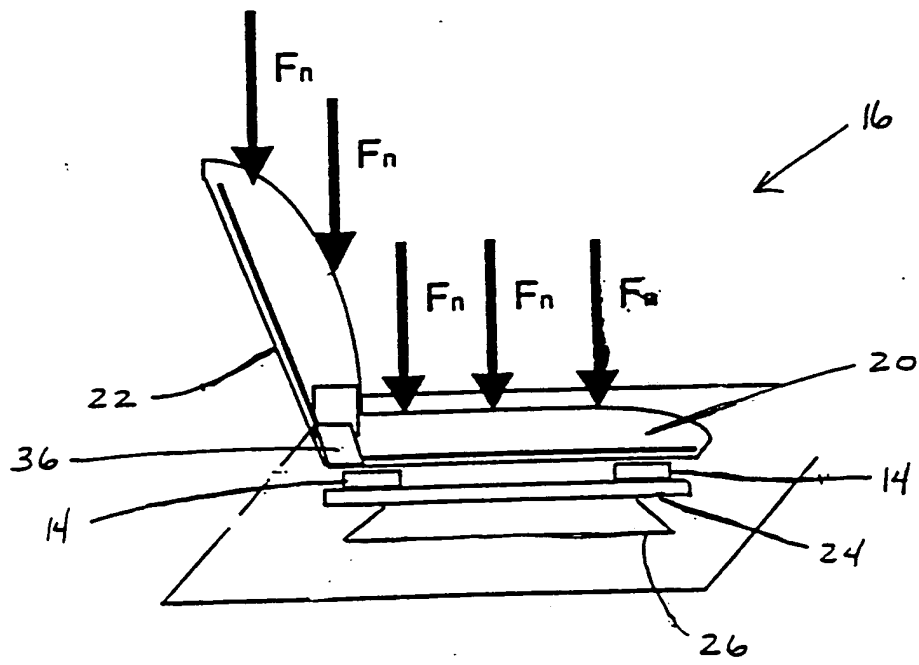


FIG. 2

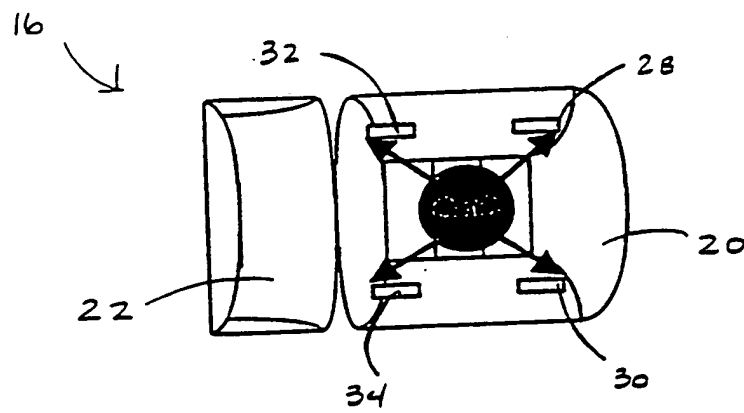


FIG. 3

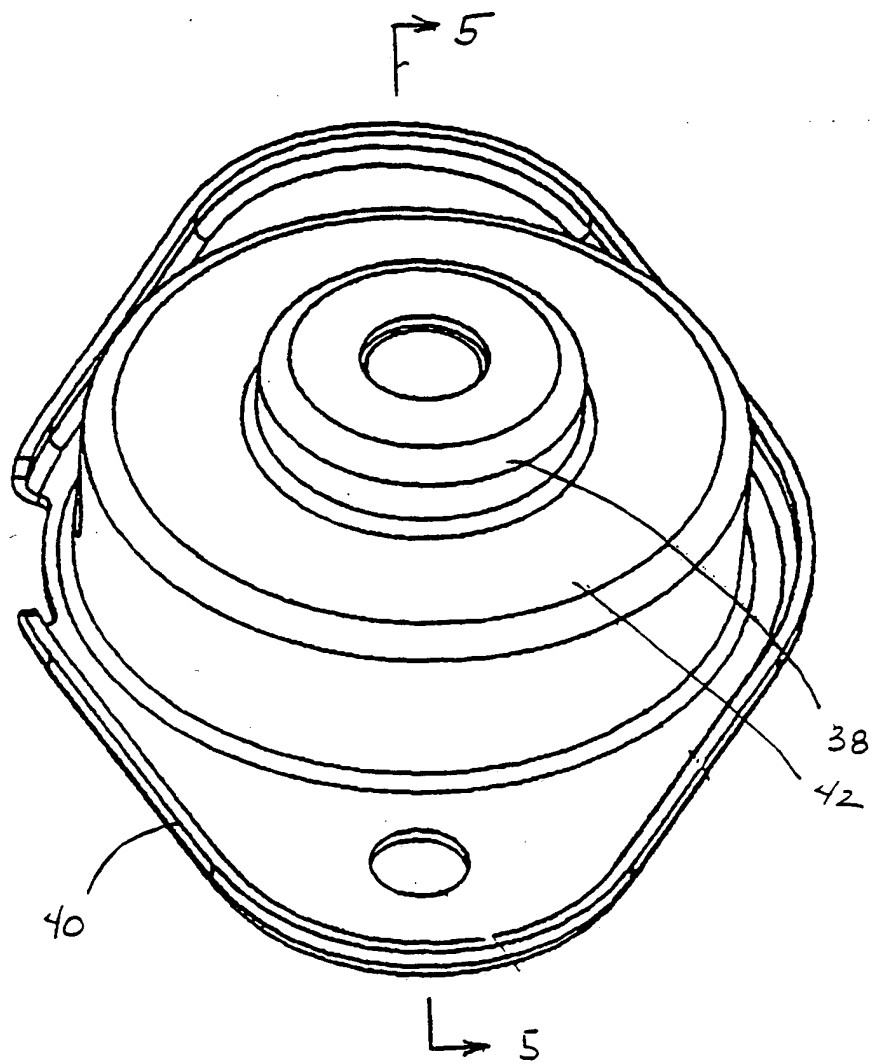


FIG. 4

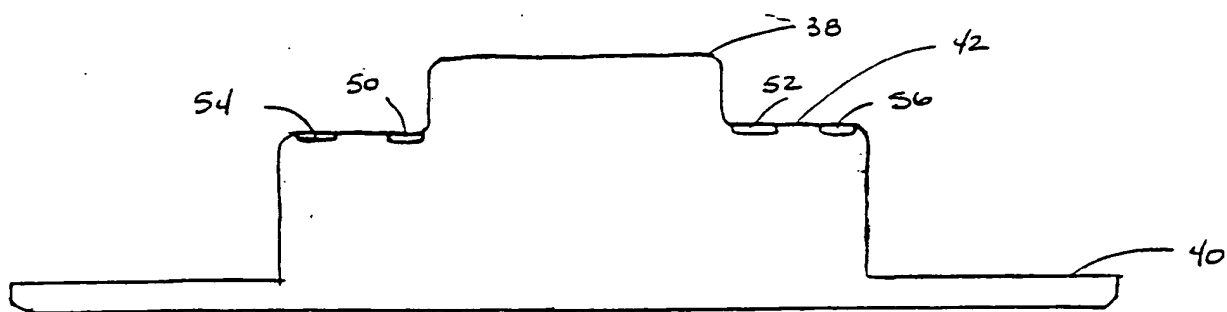


FIG. 5

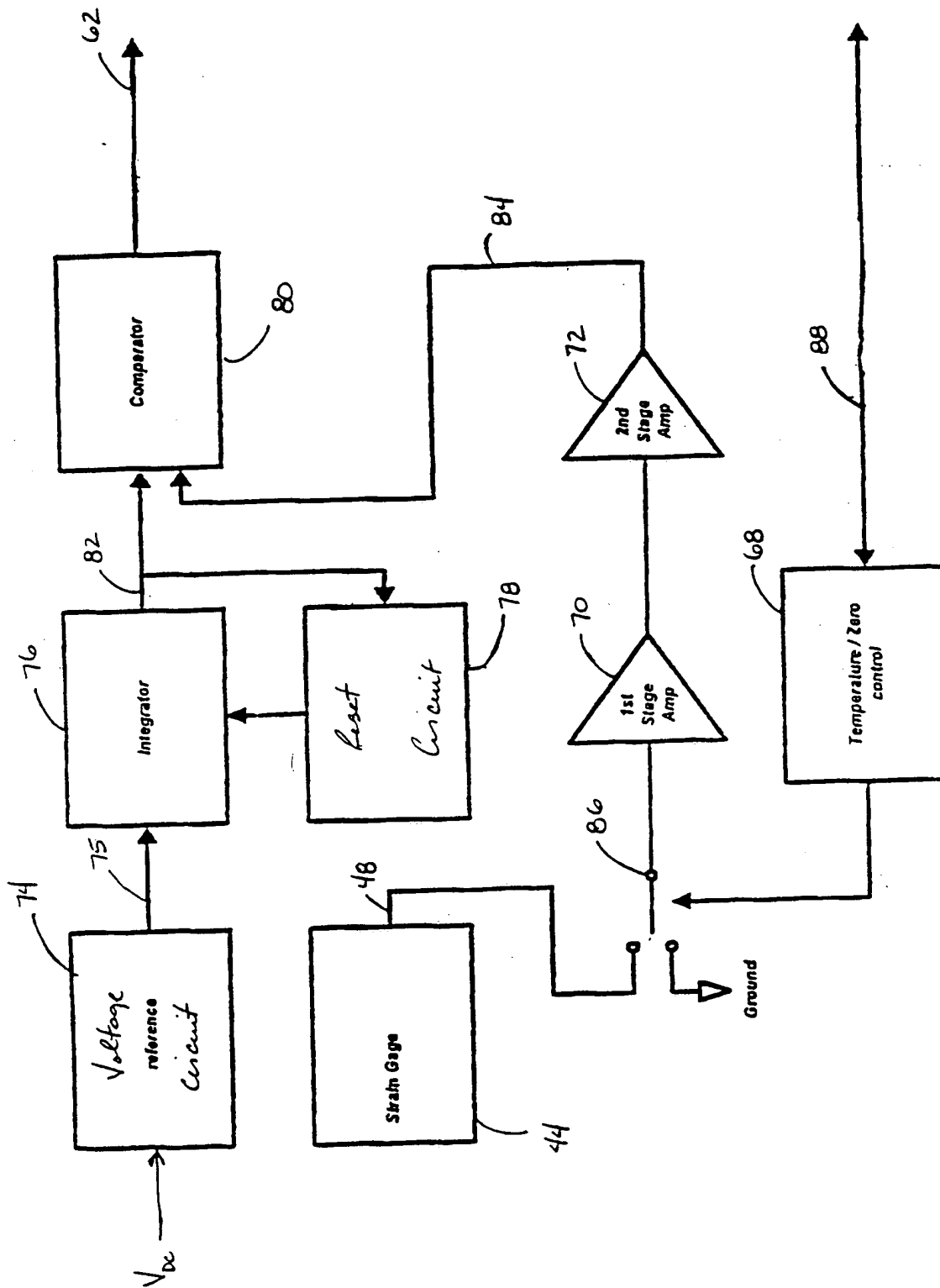


FIG. 6

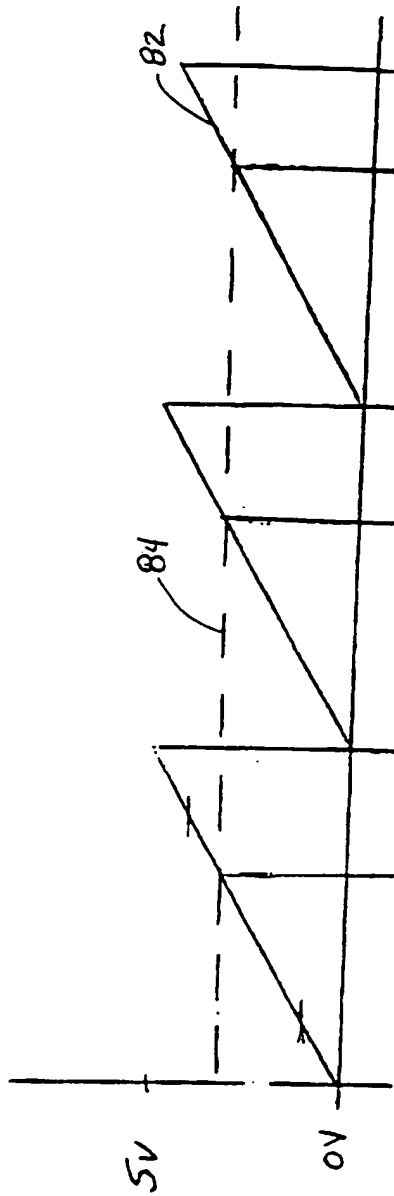


FIG. 7a

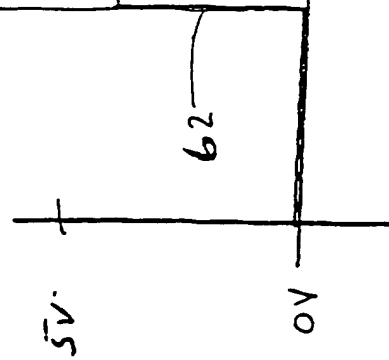


FIG. 7b

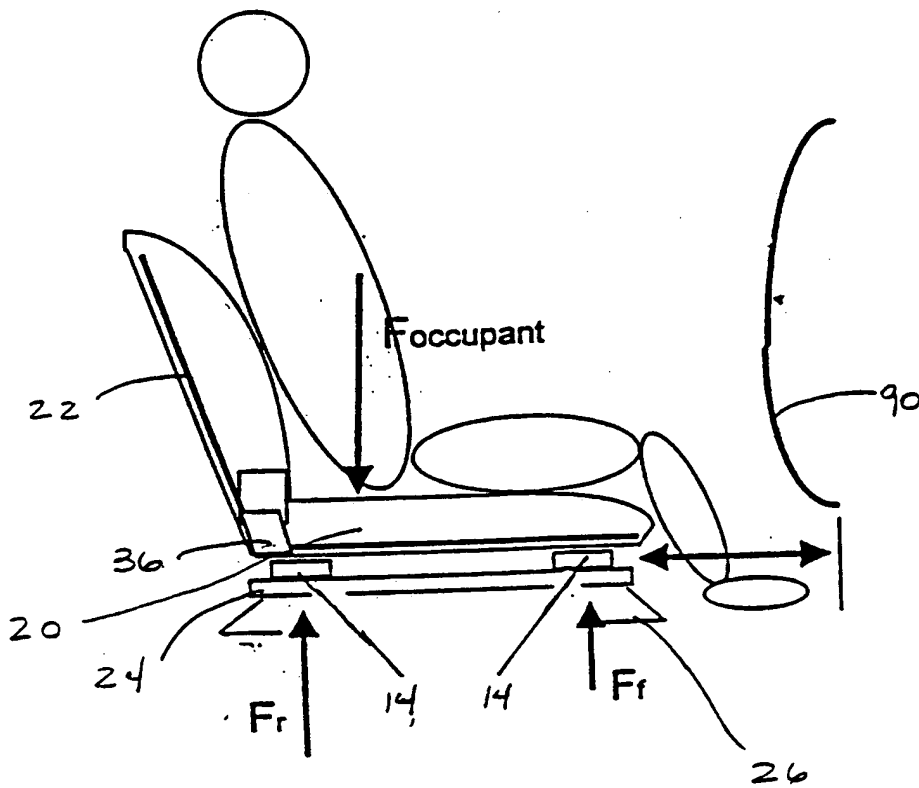


FIG. 8

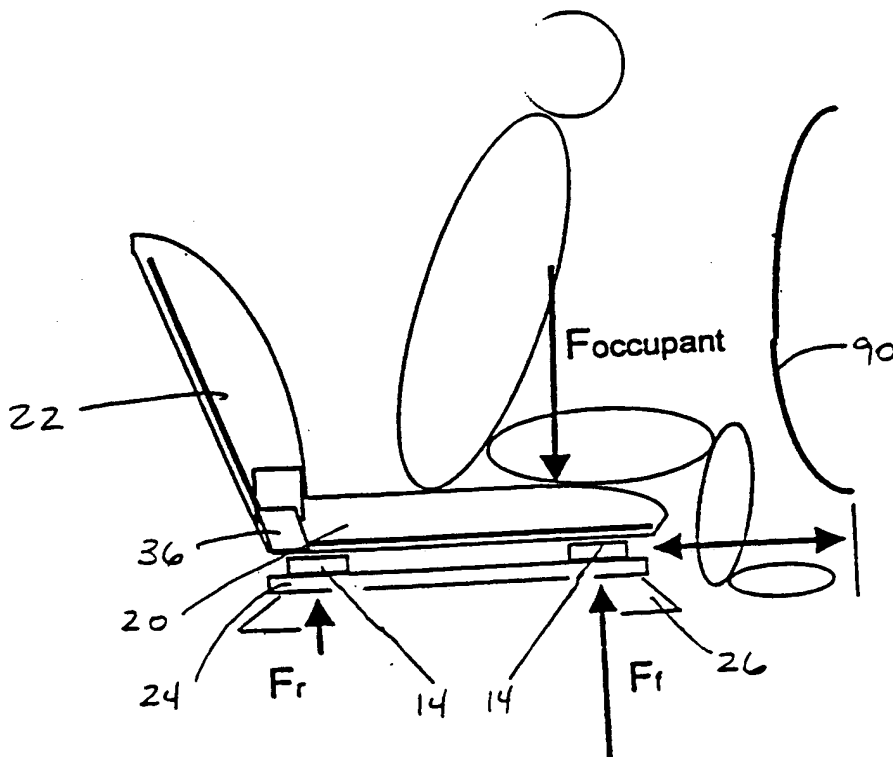


FIG. 9

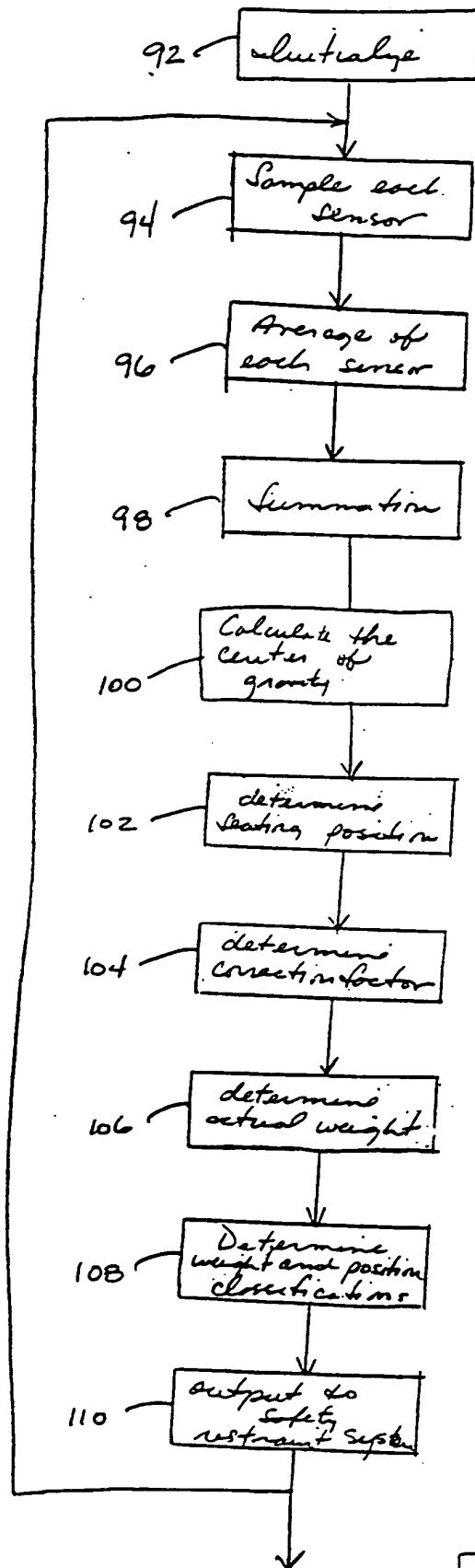


FIG. 10

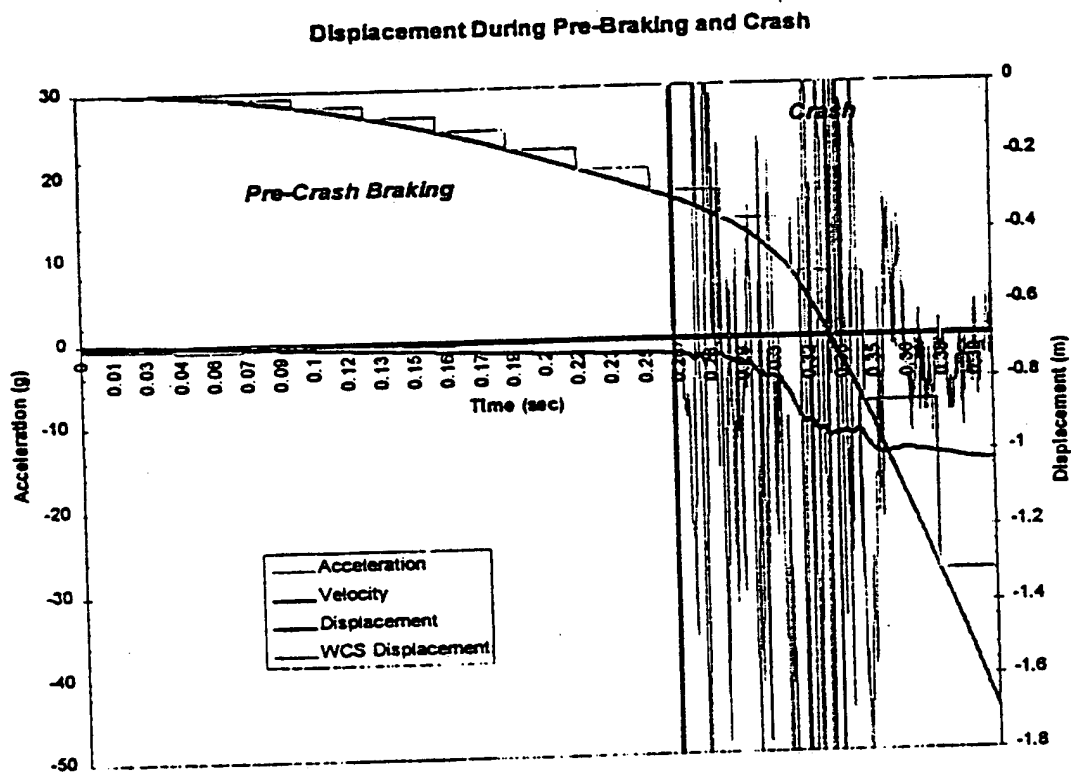


FIG. 11

INTERNATIONAL SEARCH REPORT

International Application No
PCT/US 98/24140

A. CLASSIFICATION OF SUBJECT MATTER
IPC 6 B60N2/00 B60R21/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 6 B60N B60R

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5 474 327 A (SCHOUSEK THERESA J) 12 December 1995	1
A	see column 3, line 23 - column 5, line 16; figures 1-58	17,20,33
X	WO 97 10115 A (IEE SARL ; SCHOOS ALOYSE (LU); SERBAN BOGDAN (LU)) 20 March 1997	1
A	see page 4, line 18 - page 6, line 9; figures 1,2	17,20,33
P,X	WO 98 30420 A (UNIV BOSTON) 16 July 1998 see abstract	1
P,X	WO 98 49031 A (AUTOMOTIVE SYSTEMS LAB) 5 November 1998 see abstract	1

☒ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

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- "3" document member of the same patent family

Date of the actual completion of the international search

4 March 1999

Date of mailing of the international search report

11/03/1999

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Authorized officer

Horváth, R

INTERNATIONAL SEARCH REPORT

International Application No

PCT/US 98/24140

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
E	WO 98 58821 A (SEMAP S A R L) 30 December 1998 see page 10, line 1 - page 11, line 17 -----	1

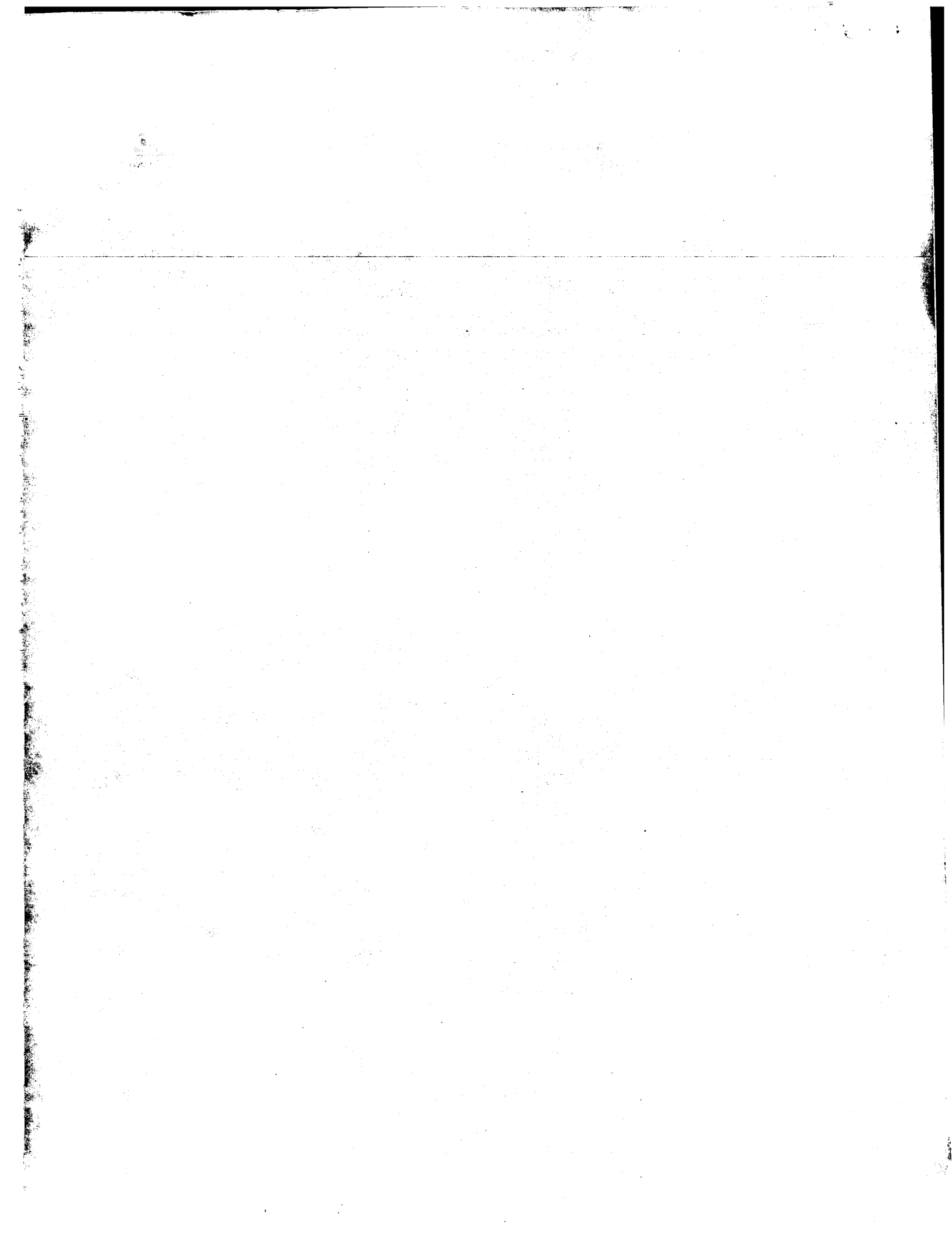
INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No

PCT/US 98/24140

Patent document cited in search report		Publication date	Patent family member(s)	Publication date
US 5474327	A	12-12-1995	EP 0721863 A	17-07-1996
WO 9710115	A	20-03-1997	LU 88655 A	12-03-1997
			EP 0850154 A	01-07-1998
WO 9830420	A	16-07-1998	US 5821633 A	13-10-1998
			AU 5912298 A	03-08-1998
WO 9849031	A	05-11-1998	NONE	
WO 9858821	A	30-12-1998	CA 2241399 A	23-12-1998



10

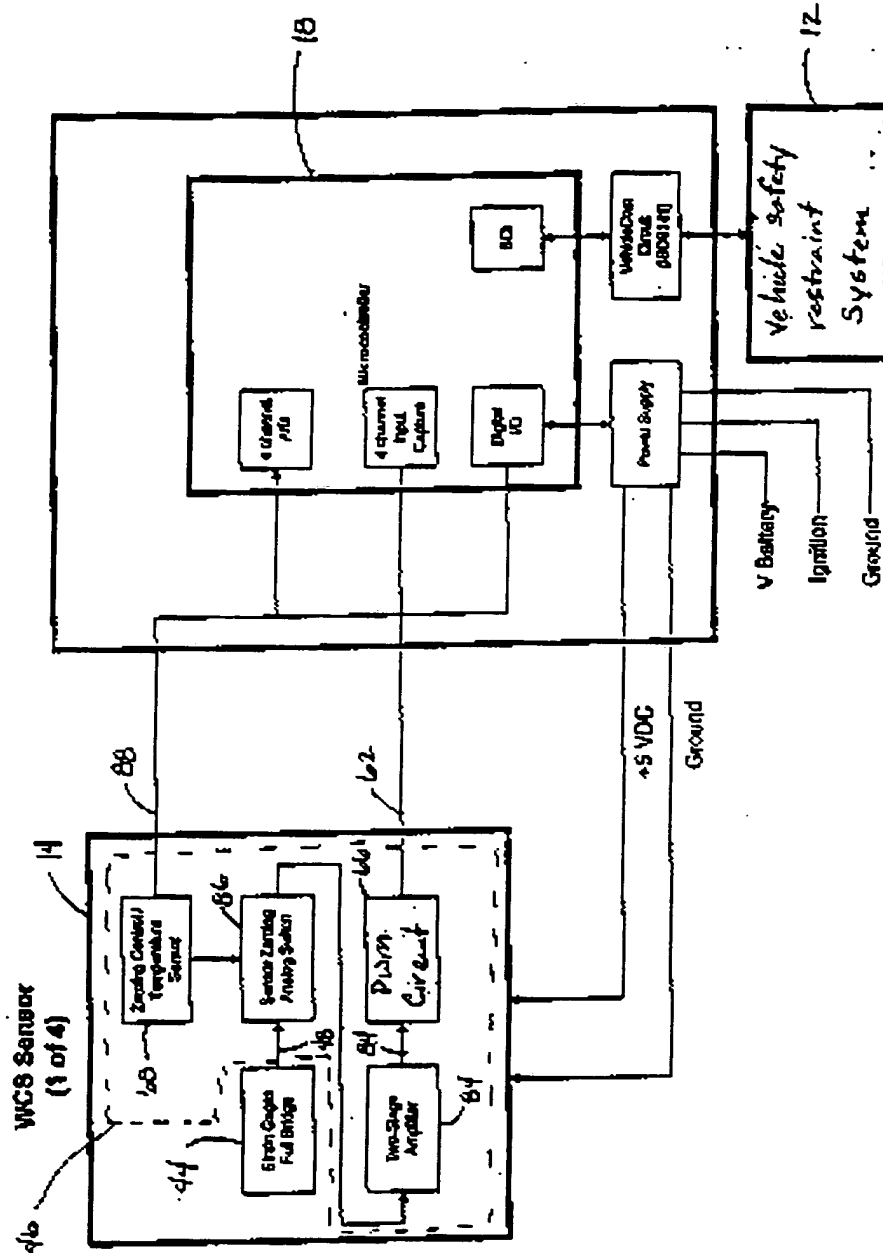
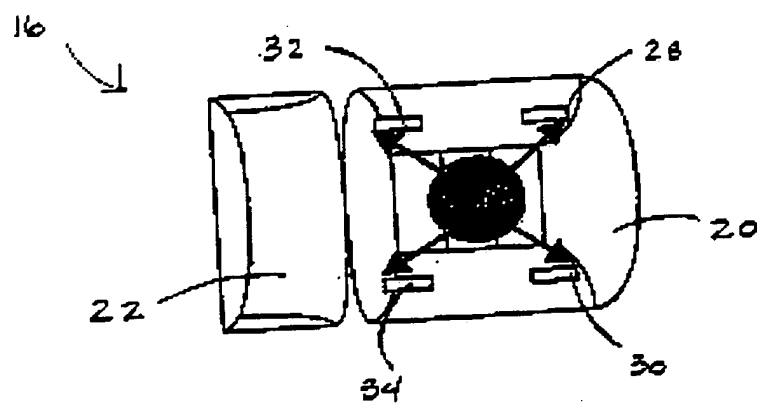
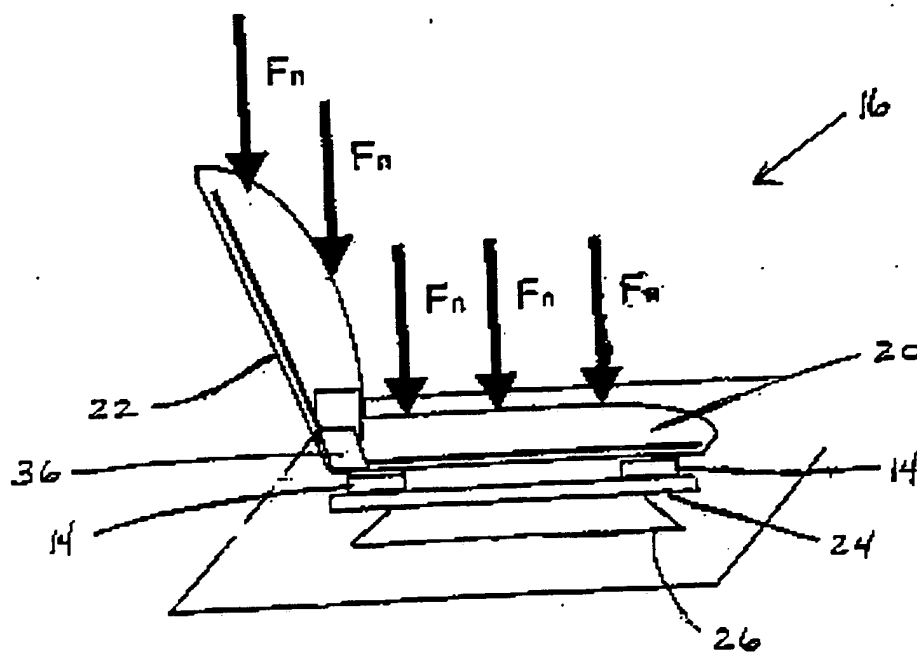
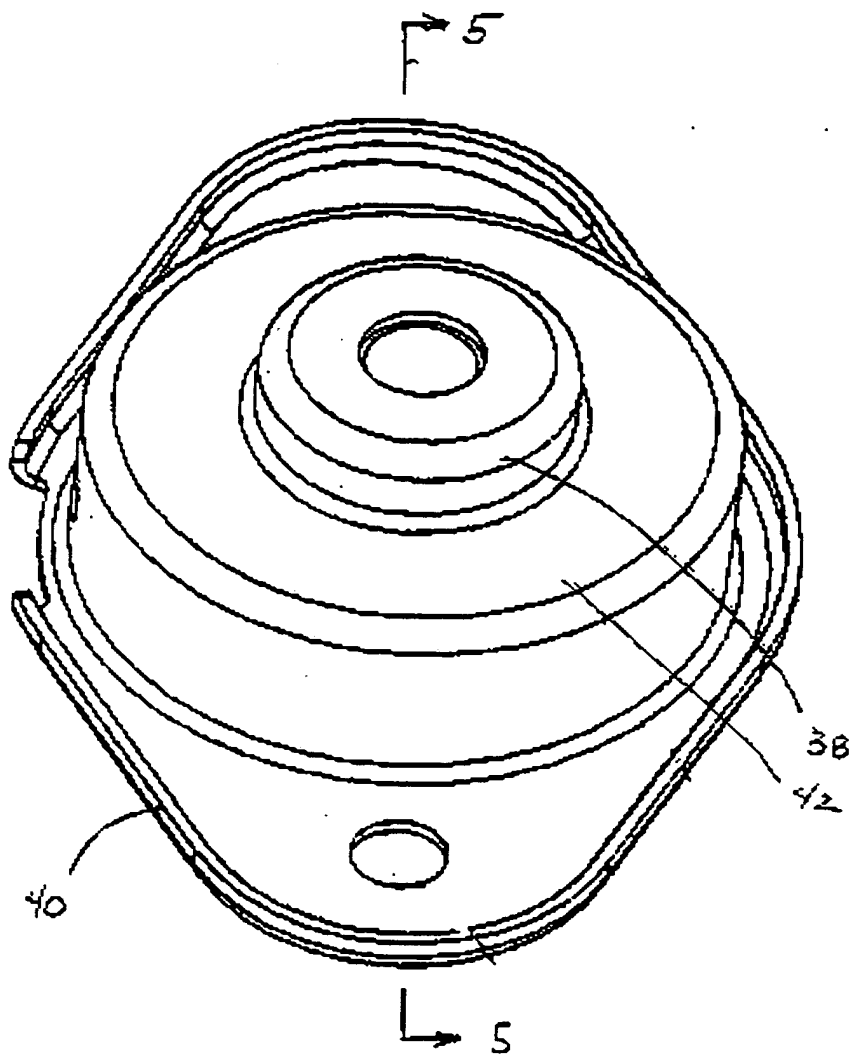


FIG. 1





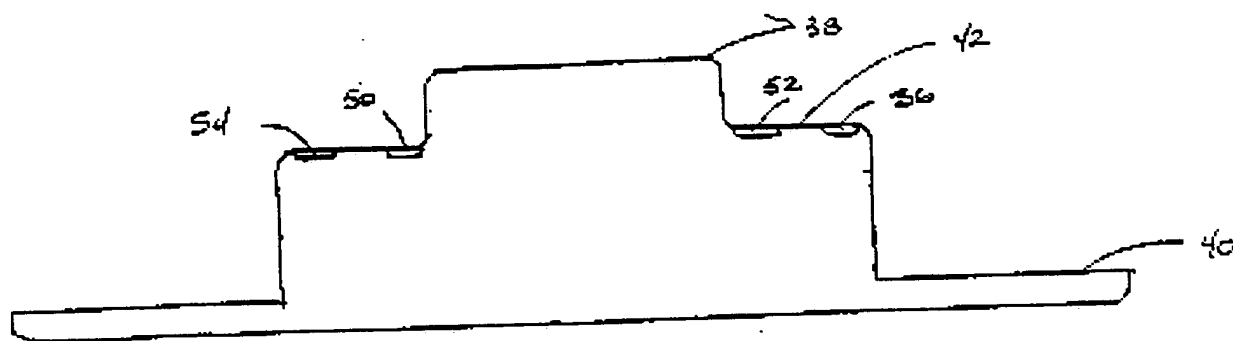


FIG. 5

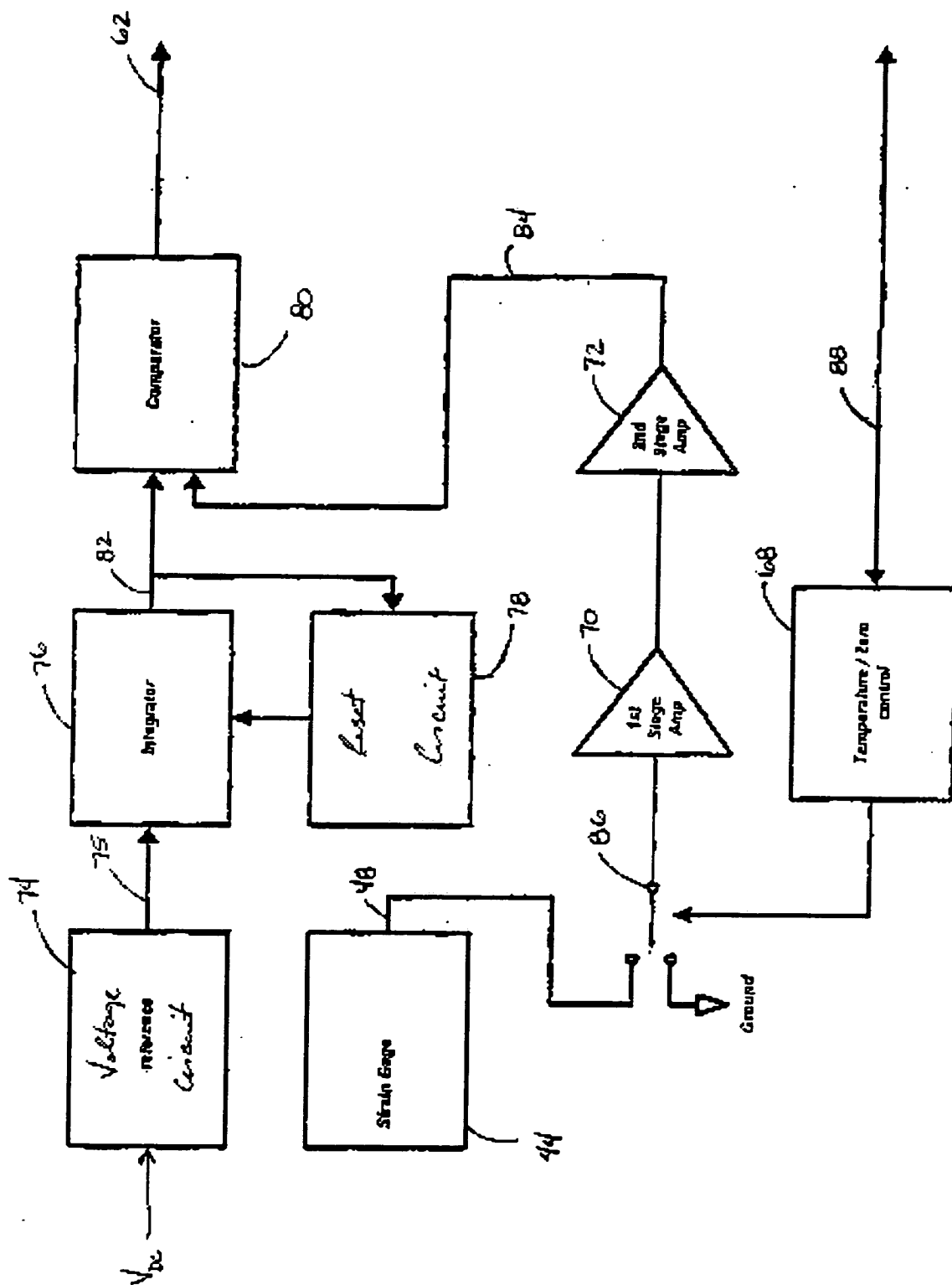
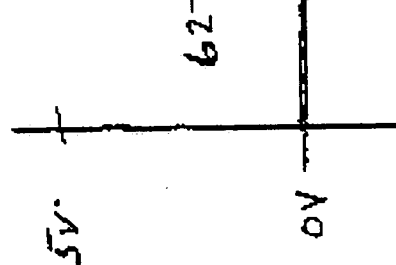
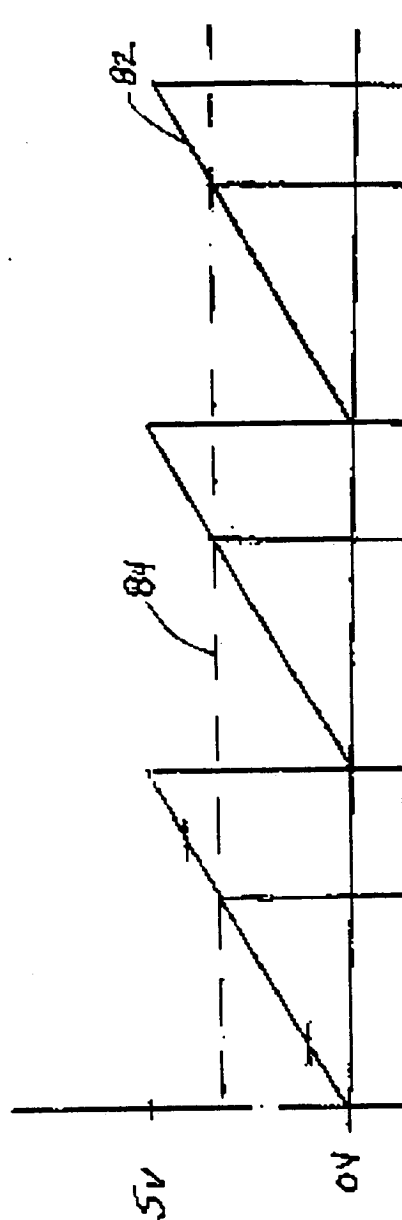


FIG. 6



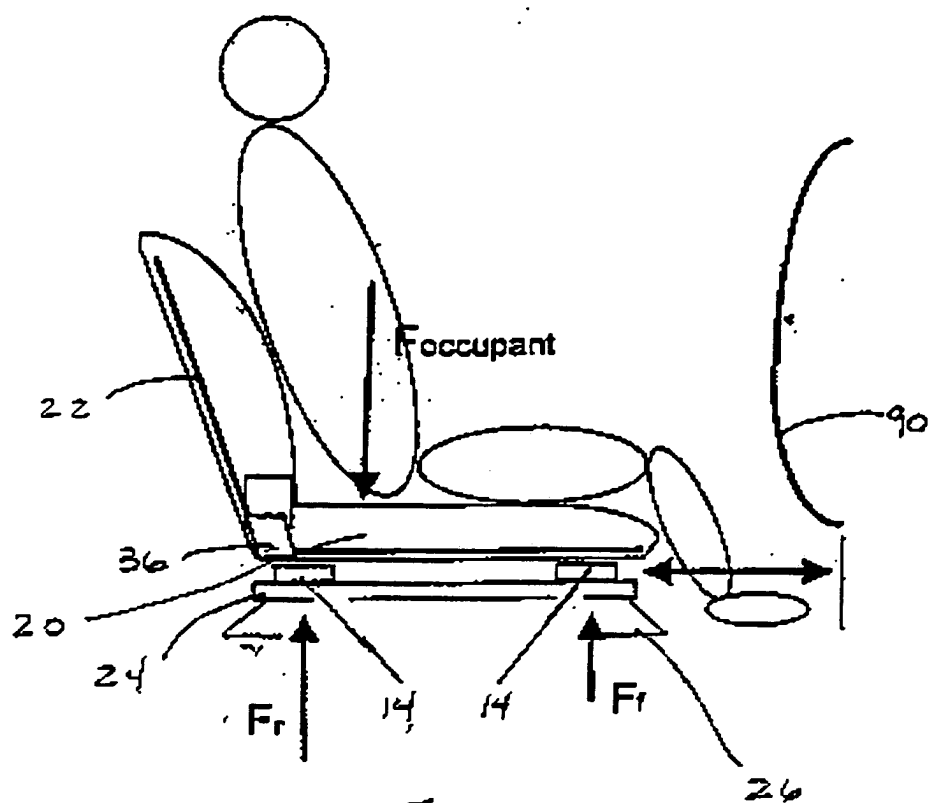


FIG. 8

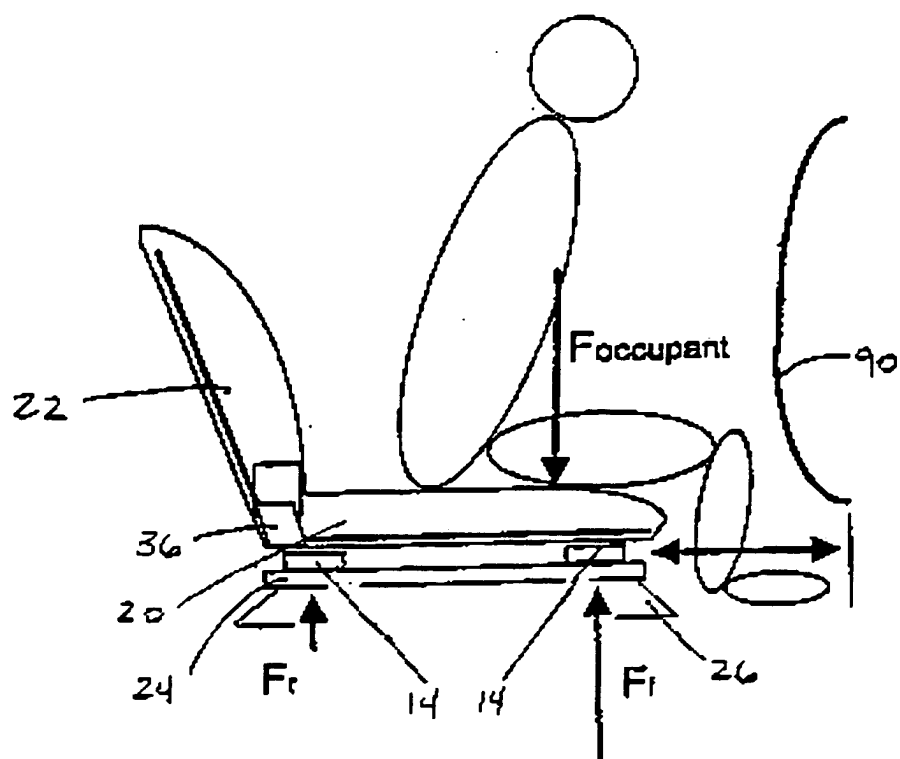


FIG. 9

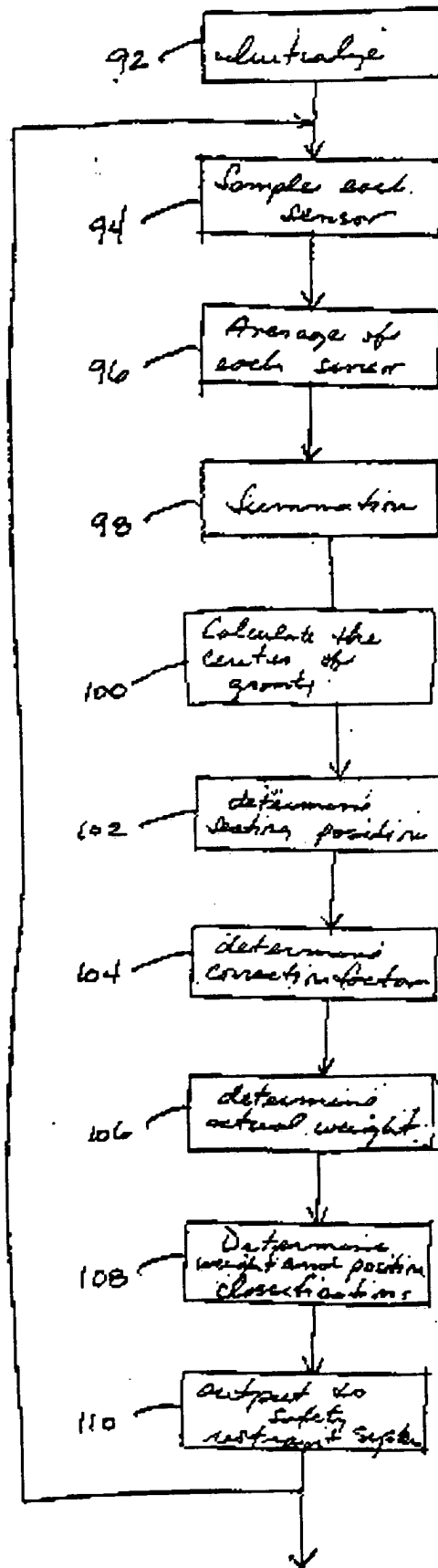


FIG. 10

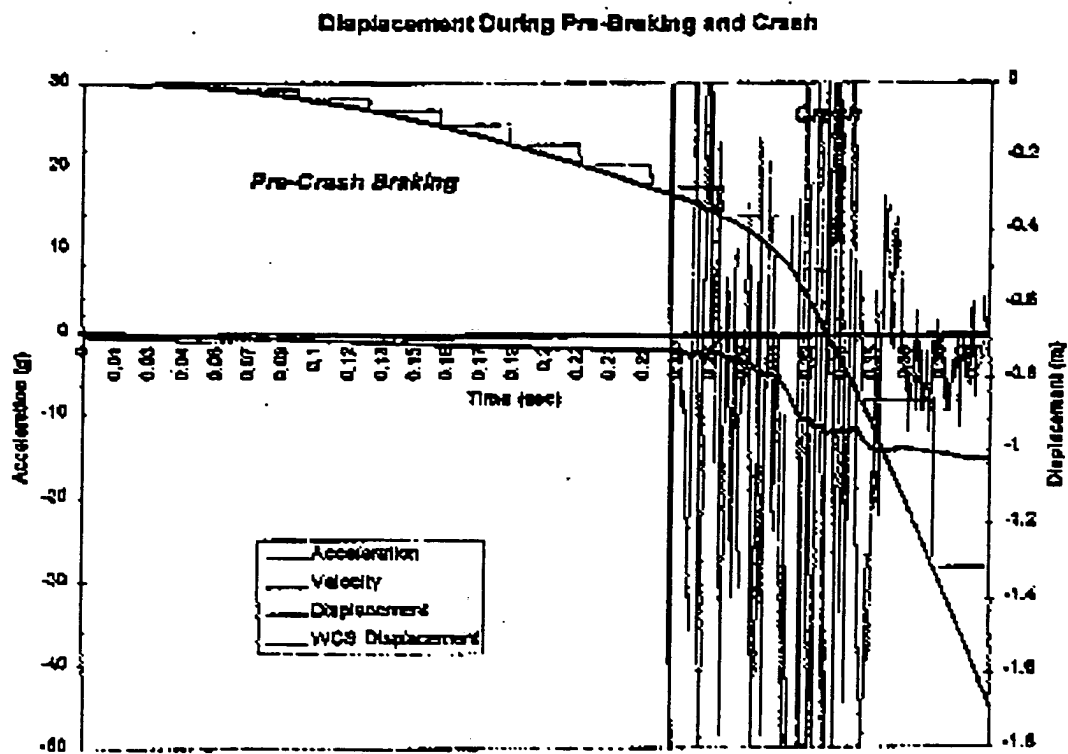


FIG. 11

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